

$$\det A = 12 - 12 = 0 \Rightarrow \text{ok, } \vec{x} \neq 0 \text{ ]}$$

(b)

$$\begin{bmatrix} 3 & 6 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(c)

$$\det A = 0 \Rightarrow \text{ok, } \vec{x} \neq 0 \text{ ]}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 2 \\ 2 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

9. Consider the following statements.

(a) Given an  $n$  by  $n$  matrix,  $A$ , if  $\det A = 0$ , then the inverse of  $A$  exists.

**T** **F** **Can't tell**

(b) If the Wronskian of two solutions of a certain linear ODE is not zero, then the solutions are linearly independent.

**T** **F** **Can't tell**

(c) Three solutions of a second order linear ODE are necessarily linearly dependent.

**T**

(d) All solutions of the differential equation  $y'' + y = 0$  can be obtained as a linear combination of the functions  $\sin(t - 1)$  and  $\sin(t + 1)$ .

**T** **F** **Can't tell**

(e) All solutions of the differential equation  $y'' + y = 0$  can be obtained as a linear combination of the functions  $\sin(t - 1)$  and  $\cos(t - 1)$ .

**T** **F** **Can't tell**

(f) If the Wronskian of two functions  $y_1(t)$  and  $y_2(t)$  is zero at  $t = t_0$ , then the two functions  $y_1(t)$  and  $y_2(t)$  are linearly dependent.

**T** **F** **Can't tell**

(g) If the Wronskian of two solutions  $y_1(t)$  and  $y_2(t)$  of a second order linear ODE is zero at  $t = t_0$ , then the two functions  $y_1(t)$  and  $y_2(t)$  are linearly dependent.

**T** **F** **Can't tell**

$$W = e^{-\int p(s) ds}$$

$$\int p(s) = -\log t \Rightarrow W = t \text{ & } t=0!$$

10. Be able to set up and solve applications-type problems such as problems 10 (financing) and 25 (mixing) in section 2.5 and problem 21 (populations) in section 2.6.

$$p(t) = -\frac{1}{t} !$$